

PAT-NO: JP02005111576A
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TITLE: INDUSTRIAL ROBOT
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INVENTOR-INFORMATION:

NAME	COUNTRY
IWAI, SEIJI	N/A
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ASSIGNEE-INFORMATION:

NAME	COUNTRY
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ABSTRACT:

PROBLEM TO BE SOLVED: To provide an origin adjusting device low in cost, high in accuracy and taking extremely little time in origin adjustment between two relatively rotating members at a joint of an industrial robot, and to provide the origin adjusting device compact, easily usable at a wrist tip shaft of the robot and dispensing with a special signal line for origin adjustment.

SOLUTION: This industrial robot is provided with a guide part 24 wherein a mounting part 23 and a positioning member 22 embedded in one or both of two relatively rotating members, slide in a projectable manner.

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